

## Network digital twin: modelling and data related challenges

Presented by:



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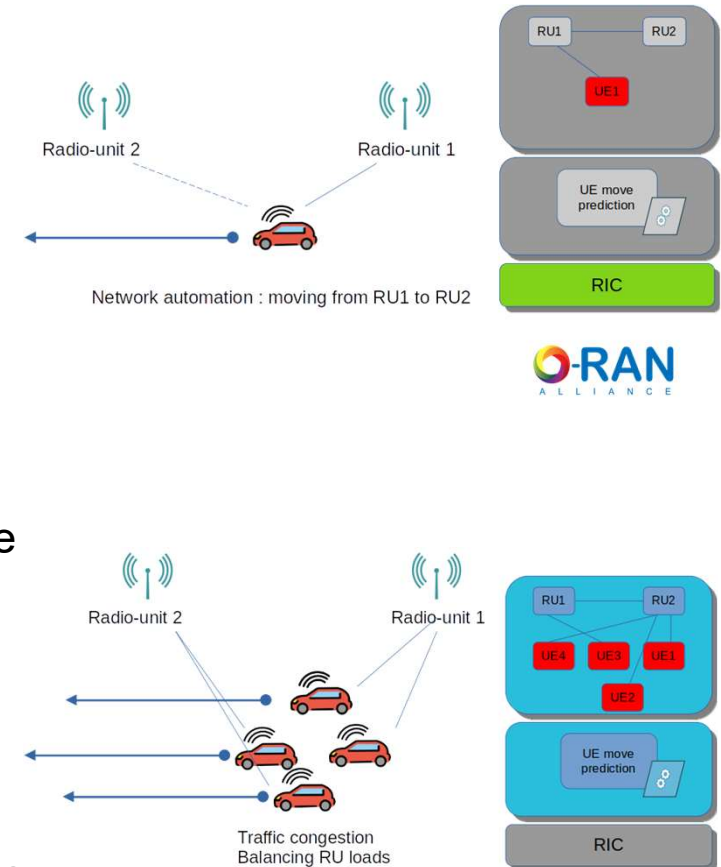


# Introduction

- Network Digital Twins (**NDT**) have emerged to deal with the increasing complexity of mobile network management and optimization
- Data is the fuel of NDT...
- ... But **data alone is not sufficient**; it must be structured, complemented by human expertise, and its semantics must be explicitly represented.
- Similarly, simulations, optimization processes, and other network functions must be explicitly modeled.

**This requires modeling**

*Such models* enable managing NDT **with situational awareness** and is a complement to intelligent network, e.g., O-RAN RIC



**Real-time monitoring**  
Complete, persistent view

**"What-if" representation for testing & data generation - simulation**  
Incomplete, on-demand view (snapshot)

**Real-world representation**

**Basic models:** representations of network components and behaviour

**Functional AI models:**

Network planning

Traffic analysis & generation

Network management & control

**Data lake:** structured and harmonised following the smart data models

Model register

**AI training / optimizer (functional models)**

**Push/request data, metrics (i.e., predicted), and models**

**Training data** (from simulation or real network)

**Trained model**

**Ideas and scenarios:** Snapshot & requirements pushed to the simulation framework

**Results, inc. linked KPIs**

**NDT management:** mapping between scenario requests and NDT's data/models/simulation; life-cycle management; link with MANO. *Worst-case: router / rule-based system / API orchestrator.*

Lifecycle management

Real-world toolbox

Testing toolbox

Link with the reality

**Zero/single-touch MANO (ETSI definition)**

Push/request data to/from the real network

Smart Data Models

Effect changes

**Harmonised data collection:** telemetry collector, databases, data buses, ...

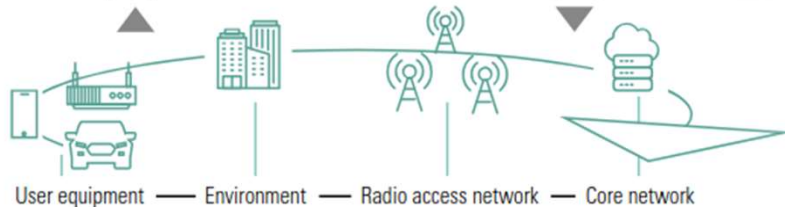
**Network planning, management and control**

**RIC**

RIC tester

Real CU/DU/RU:ACC, PX, ...

**Core:** Free5GC, OAI, ...



6G-TWIN  
architecture

Unified dashboard

Use-case  
instantiation &  
results

# 6G-Twin Architecture

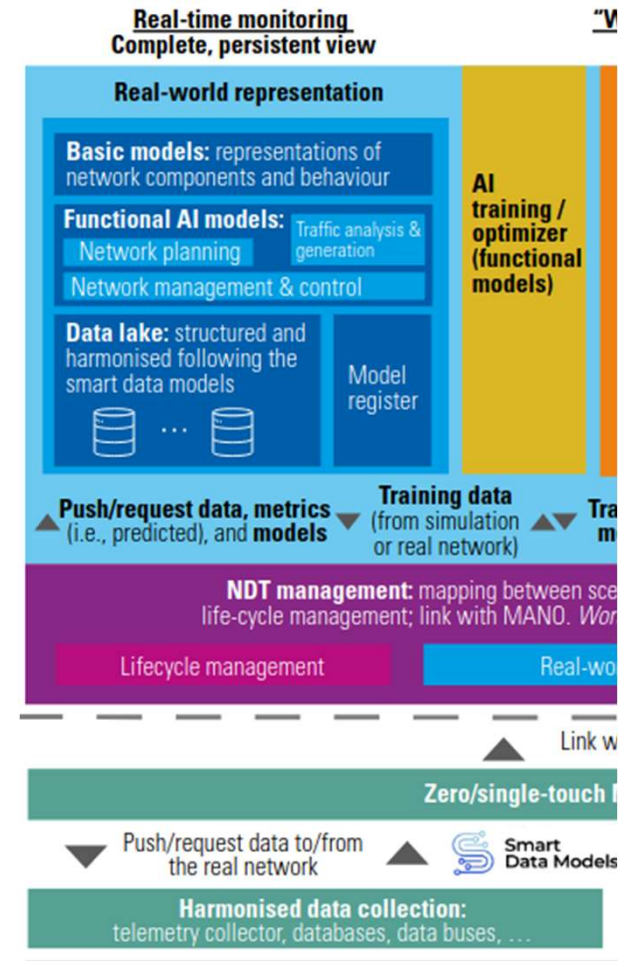
Human  
World



<https://6g-twin.eu/>

# Focus on models & data collection

- ITU-IT 309x inspired
- Basic models: assets and network data representation (structural model)
- Functional model: network dynamic aspect, management, predictions
- Data harmonization: at data collection (telemetry); reinforced by data models.



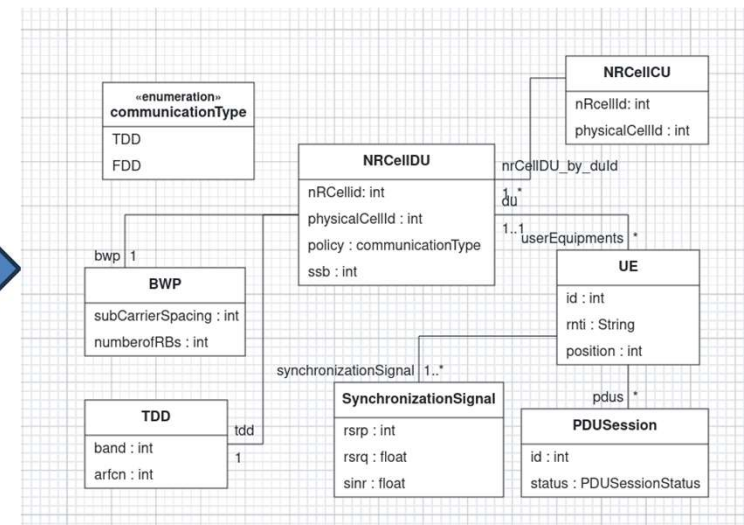


# Building a basic model

From standard(s)

Category	Data name (3GPP TS 38.215)	Data description
Synchronization signal (SS)	SS reference signal received power (SS-RSRP) SS reference signal received quality (SS-RSRQ) SS signal-to-noise and interference ratio (SS-SINR) SS reference signal received power per branch (SS-RSRPB) SS reference signal antenna relative phase (SS-RSARP)	Synchronization signal (SS) is used to synchronize UE with a gNB. These signals consist of the Primary Synchronization Signal (PSS) and the Secondary Synchronization Signal (SSS).
Channel State Information (CSI)	CSI reference signal received power (CSI-RSRP) CSI reference signal received quality (CSI-RSRQ) CSI signal-to-noise and interference ratio (CSI-SINR)	Channel State Information (CSI) reference signals are transmitted according to TS 38.211 and used by the UE to estimate the channel and report channel quality information (CQI Channel Quality Indicator) to the gNB.
Global navigation satellite system (GNSS)	UE GNSS Timing of Cell Frames for UE positioning for E-UTRA UE GNSS code measurements UE GNSS carrier phase measurements	UE location-related measurements via GNSS.
Wireless Local-Area Network (WLAN)	IEEE 802.11 WLAN RSSI	Received Signal Strength Indicator (RSSI) from IEEE 802.11 WLAN.
Evolved Universal Terrestrial Radio Access (E-UTRA)	Reference signal time difference (RSTD) for E-UTRA System Frame Number (SFN) and frame timing difference (SFTD) E-UTRA RSRP E-UTRA RSRQ E-UTRA RS-SINR	Measurements related to E-UTRA, used by the UE for synchronisation and channel quality estimation.
Sounding Reference Signal (SRS)	SRS reference signal received power (SRS-RSRP)	The SRS transmission occurs periodically on a non-primary set of carriers and at appropriate power levels, such that a gNB can measure the quality of its synchronization to the UE that it is serving.

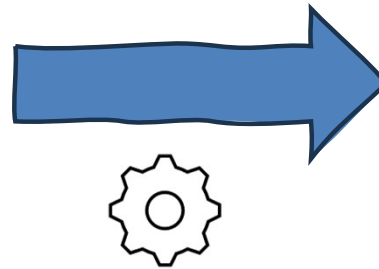
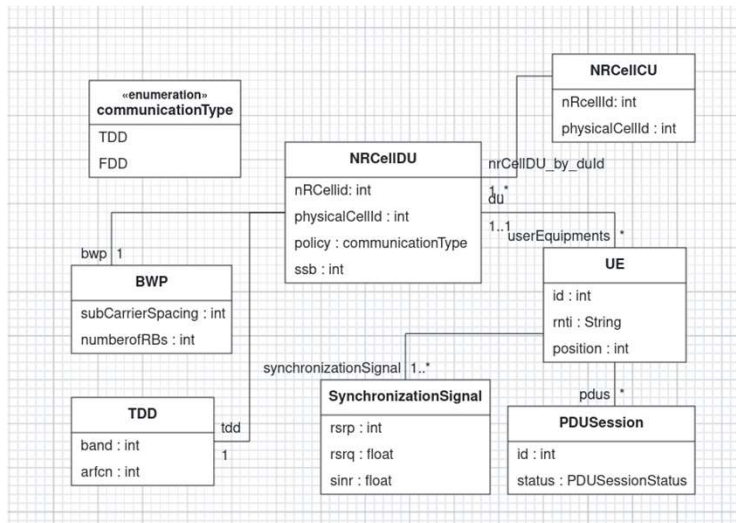
3GPP Standard +  
requirements for NDT



Basic model  
UML representation  
(excerpt)

# Generating common schema

## Basic model



```
},
"id": {
  "type": "string",
  "description": "Property. Model: 'https://schema.org/Text'. id valu
},
"position": {
  "type": "string",
  "description": "Property. Model: 'https://schema.org/Text'. position
},
"rnti": {
  "type": "string",
  "description": "Property. Model: 'https://schema.org/Text'. rnti va
},
"du": {
  "description": "Relationship. Model: 'https://schema.org/URL'. Refe
  "type": "string",
  "format": "uri"
},
"pdus": {
  "type": "array",
  "items": {
    "description": "Relationship. Model: 'https://schema.org/URL'. Re
    "type": "string",
    "format": "uri"
  }
},
"synchronizationSignal": {
  "type": "array",
  "items": {
    "description": "Relationship. Model: 'https://schema.org/URL'. Re
```

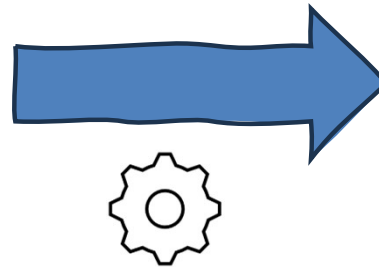
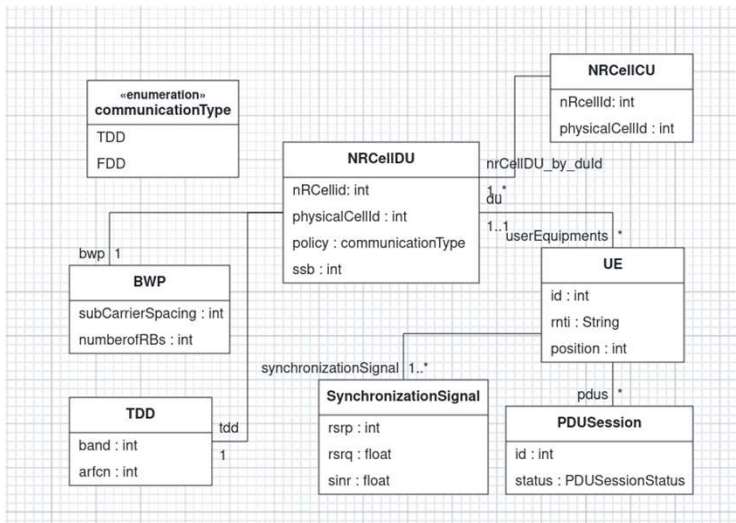


<https://besser.readthedocs.io>

NSGI-LD (here in Json-LD)  
specification for harmonization

# Generating operational representation

## Basic model



```
type UE {
  // position will be the prepared points on the floor map
  id: int;
  rnti: String;
  pdu: nodeList<PDUSession>;
  du: node<NRCellIDU>;
  position: int;
  connected: bool?;
  synchronizationSignal: nodeTime<SynchronizationSignal>;
}

type SynchronizationSignal {
  rsrp: int;
  rsrq: float;
  sinr: float;
}

type PDUSession {
  id: int;
  status: PDUSessionStatus;
}

enum PDUSessionStatus {
  ESTABLISHED("established");
}
```

Operational Digital Twin basic model



<https://besser.readthedocs.io>



```

// position will be the prepared points on the floor map
id: int;
rnti: String;
pdus: nodeList<PDUSession>;
du: node<NrCellDU>;
position: int;
connected: bool?;
synchronizationSignal: nodeTime<SynchronizationSignal>;
}

type SynchronizationSignal {
  rsrp: int;|
  rsrq: float;
  sinr: float;
}

type PDUSession {
  id: int;

```

model.nrCellCU\_by\_nRCellid X model.nrCellCU\_by\_index

model.nrCellCU\_by\_nRCellid > node:2000 > nodeList:1001 > node:5000 > nodeTime:4000 > nodeList:100f > nodeTime:4001

nodeTime:4001

Total size	From	To	Max rows
59	01 / 01 / 1970, 00:01:00.000	01 / 01 / 1970, 00:59:00.000	59

Max dephasing

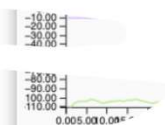
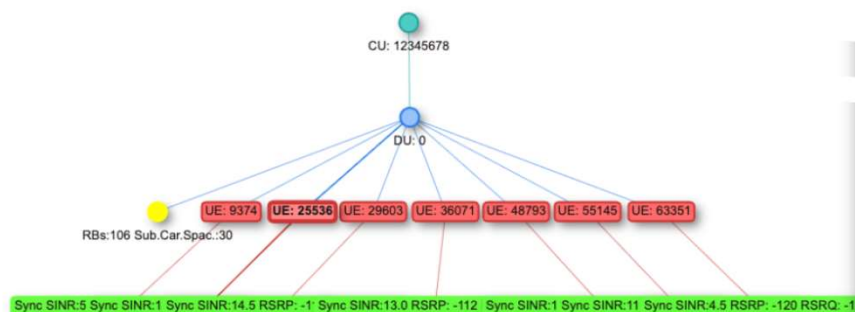
Duration microseconds

Table Chart

Mappings

Q Filter the table...

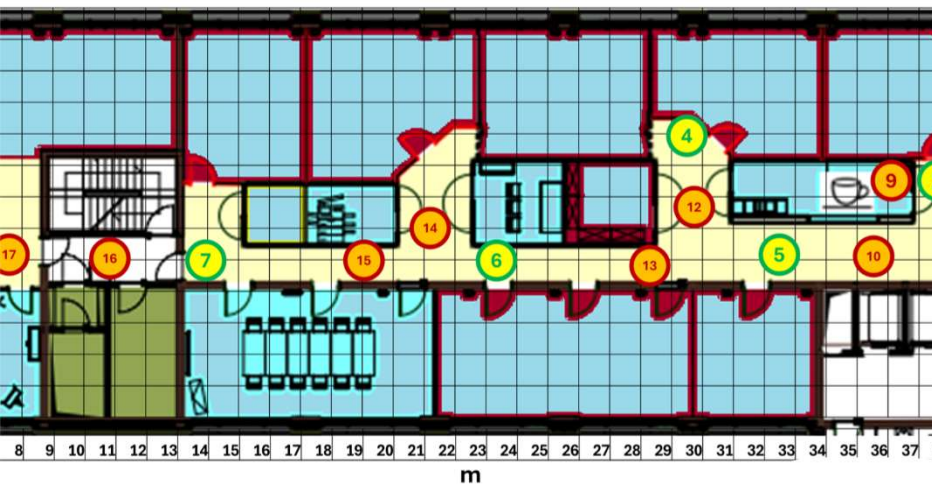
Column 0 core::time	Column 1 model::SynchronizationSignal
01/01/70, 12:01:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:02:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:03:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:04:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:05:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:06:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:07:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:08:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:09:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:10:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:11:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:12:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:13:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:14:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:15:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }
01/01/70, 12:16:00 AM GMT	model::SynchronizationSignal { rsrp, rsrq, sinr }



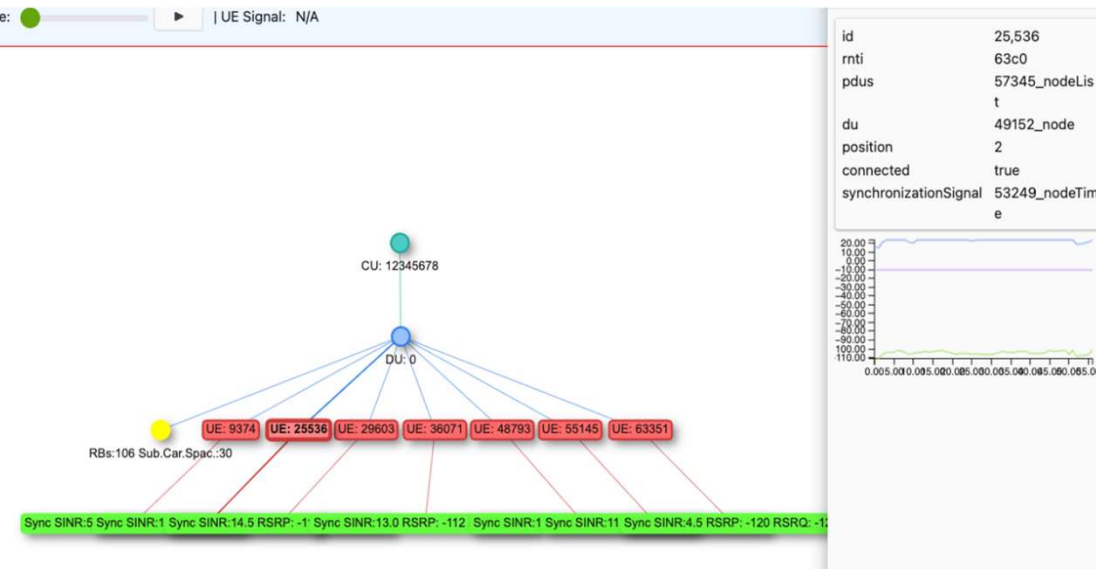
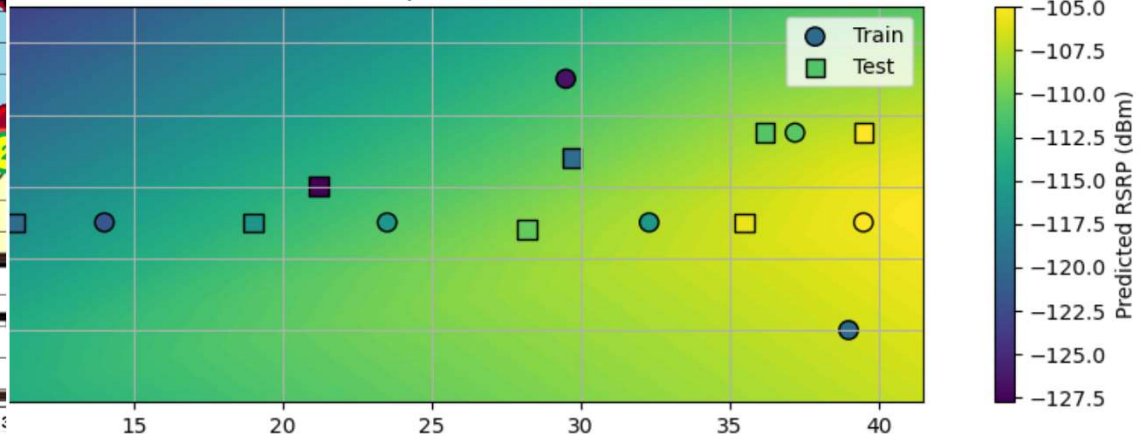
# Implementation

## Proof of Concept



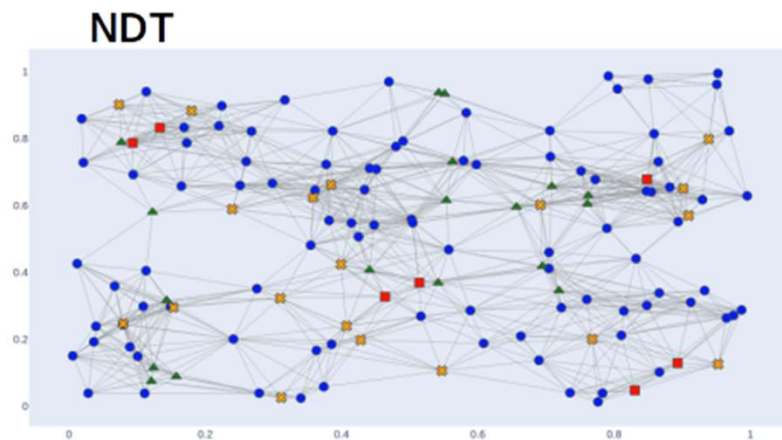


Predicted RSRP Map with CNN



Functional model:  
prediction  
Proof of Concept

# Connecting to simulation

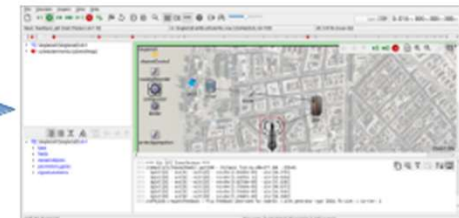


(Near) Real-time large-scale monitoring

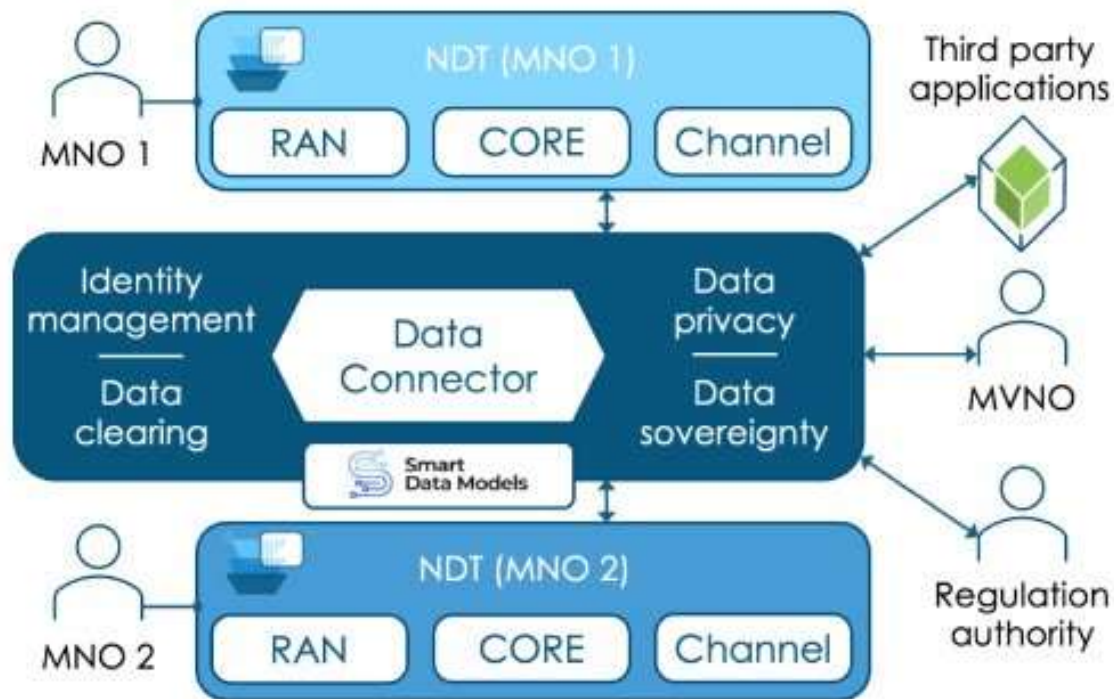


Scaling :  
- Time  $t$ ,  
- Area  $x,y$   
- simulation scenario

Simulation environment



Offline small to medium scale  
Simulation



Inter-Network  
data exchange  
and  
harmonization  
(See the poster  
session)

# Security Threats and opportunities

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- Centralising information in NDT is a potential huge risk!
  - It could be a single attack point to get access to everything in the network...





# Security Threats and opportunities

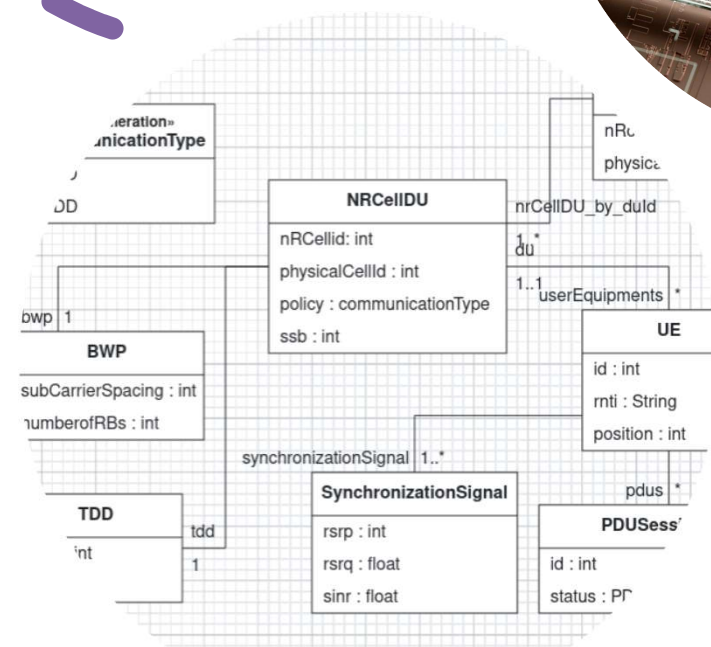
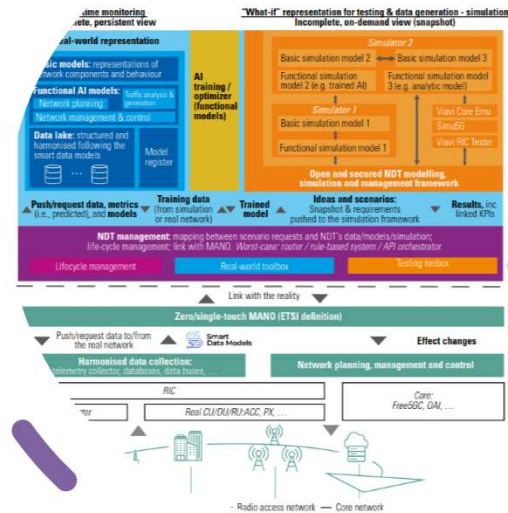
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- Need to secure data transfer
  - Data trust, validation, provenance, privacy preservation,
  - Separation of real time vs historical
- Need to secure feedback-loop
  - The NDT should not become the network controller (limiting the radius of action)
- Provide human-approved for impacting decision
  - Validating any decision proposed by the NDT



# Conclusion

- **NDT architecture** – *Complementing Smart Network* (e.g., ORAN) - inspired by ITU-T 309x specifications
- **Standard format for data** harmonization and exchange expressed in ETSI **NSGI-LD** information model (ETSI GS CIM)
- Operational DT prototype implementation:
  - Systematic modelling : basic model derived from standard
  - Supported by an E.U. solution (Greycat)
  - Pending integration of functional models and simulators
- **Security is a major concern** due to the comprehensive nature of NDT and its potential impact on the real network.



Additional slides for (eventual) questions

# Secure the Data Pipeline

- Cryptographic authentication of all telemetry sources (mTLS, signed streaming)
- Strong provenance tracking (who/what/when produced data)
- Data validation & sanity checks (range, rate, topology consistency)
- Separation of real-time vs historical ingestion paths
- Immutable raw data storage (append-only logs)



# Secure the functional models

- Sandboxed execution environments (VMs, enclaves)
- Resource caps (CPU, memory, time)
- Explainability hooks for optimization outputs
- Detection of adversarial input patterns
- Explicit failure modes (no silent fallback)

# Governance & Process

- Clear ownership of model correctness
- Formal validation before using twin outputs operationally
- Separation of duties: Model builders  $\neq$  operators  $\neq$  approvers
- Documented failure modes and “safe shutdown” paths
- Legal & compliance review (data retention, cross-border data)